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This can be seen through the following two examples: This type of decomposition is 1. The LTI system especially useful to build systems in Simulink r.  $\dot{x} = x + u$ ,  $y=x$  STATE-SPACE LINEAR SYSTEMS 9 (a)  $\dot{x} = x + u$ ,  $y = x$  (b) LTI system in (1.4) Figure 1.2. Block diagram representation systems.

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