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Norman S. Nise teaches in the Electrical and Computer Engineering Department at California State Polytechnic University, Pomona. In addition to being the author of Control Systems Engineering, Professor Nise has contributed to the CRC publications The Engineering Handbook, The Control Handbook,

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Yes - power gain, remote control, parameter conversion; No -
Expense, complexity 3. Motor, low pass filter, inertia supported
between two bearings 4. Closed-loop systems compensate for
disturbances by measuring the response, comparing it to the
input response (the desired output),...

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Nise

Control systems engineering nise solution_manual 1. O N E Introduction ANSWERS TO REVIEW QUESTIONS 1. Guided missiles, automatic gain control in radio receivers, satellite tracking antenna 2. Yes - power gain, remote control, parameter conversion; No - Expense, complexity 3.

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8 Solutions to Skill-Assessment Exercises $e^{v_0} + \delta v = e^{v_0} + de v$
 $dv v_0 \delta v = e^{v_0} + e^{v_0} \delta v$ Substituting into Eq. (1) $d\delta v dt + e^{v_0} + e^{v_0} \delta v - 2 = i(t)$ (2) Setting $i(t) = 0$ and letting the circuit reach steady state, the capacitor acts like an open circuit. Thus, $v_0 = v_r$ with $i_r = 2$. But, $i_r = e v_r$ or $v_r = \ln i_r$. Hence, $v_0 = \ln 2 = 0.693$. Substituting this value of v_0 into Eq. (2) yields

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Chapters 6, 7, 8, and 9 return to control systems analysis and design with the study of stability (Chapter 6), steady-state errors (Chapter 7), and transient response of higher-order systems using root locus techniques (Chapter 8). Chapter 9 covers design of compensators and controllers using the root locus.

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